

**Data input**

# Data input

- data input involves digital encoding of both:
  - geographic data (boundaries, point locations), and
  - and attribute data (tables, documents, photos, video)

# Data input

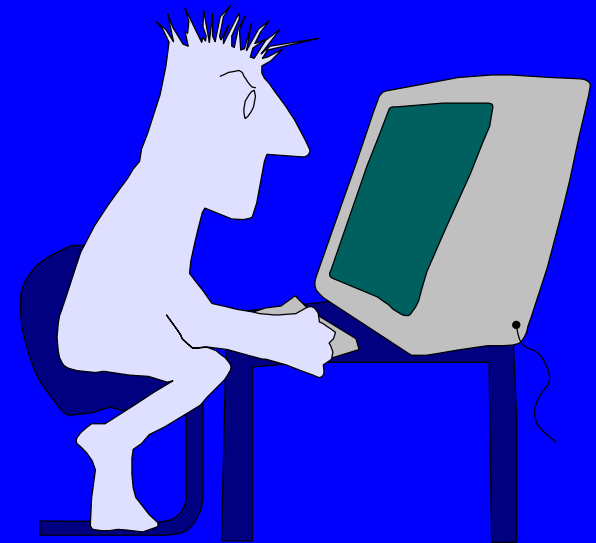
- **conversion of hardcopy to digital maps is the most time-consuming task in GIS**
  - **up to 80% of project costs**
  - **estimated to be a US \$10 billion annual market**
  - **labor intensive, tedious and error-prone**
  - **database development sometimes becomes an end in itself**

# Geographic data input

- keyboard entry of coordinates
- digitizing
- scanning and raster to vector conversion
- field work data collection using global positioning systems
- air photos and remote sensing

# Keyboard entry

- keyboard entry of coordinate data
- e.g., point lat/long coordinates
  - from a gazetteer (a listing of place names and their coordinates)
  - from locations recorded on a map

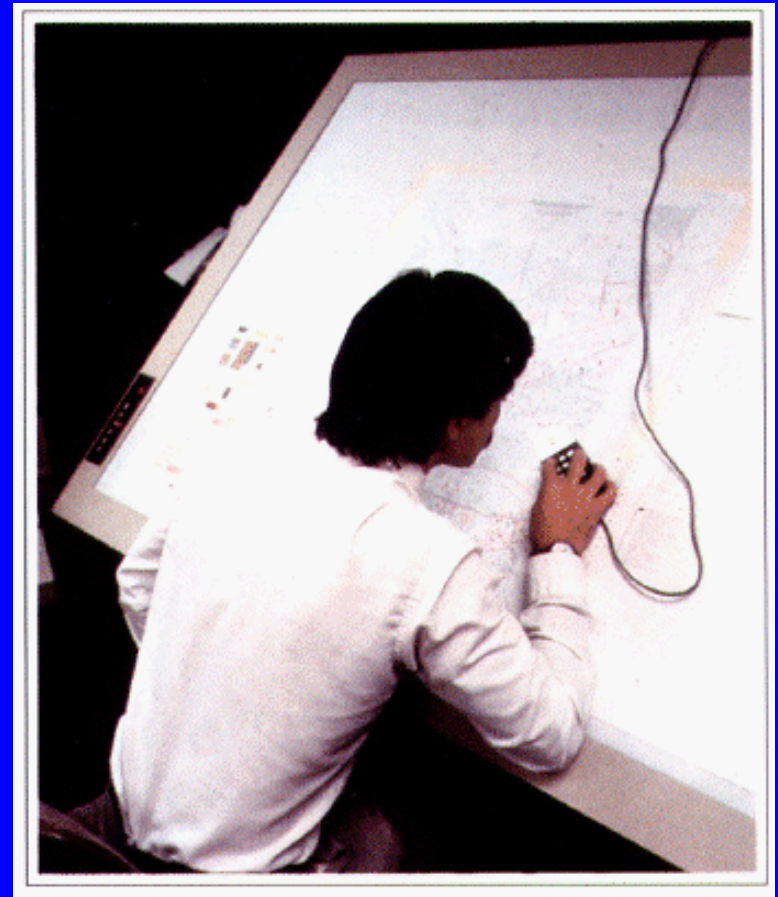


# Latitude/longitude coordinate conversion

- latitude is y-coo, longitude is x-coo!
- common format is  
degrees, minutes, seconds  
113° 15' 23" W    21° 56' 07" N
- to represent lat/long in a GIS, we need  
to convert to decimal degrees  
-113.25639    21.93528
- $DD = D + (M + S / 60) / 60$

# Manual digitizing

- digitizing tables
- 25 x 25cm to 200 x 150cm
- cost 300\$ to 5000\$
- most common form of coordinate data input



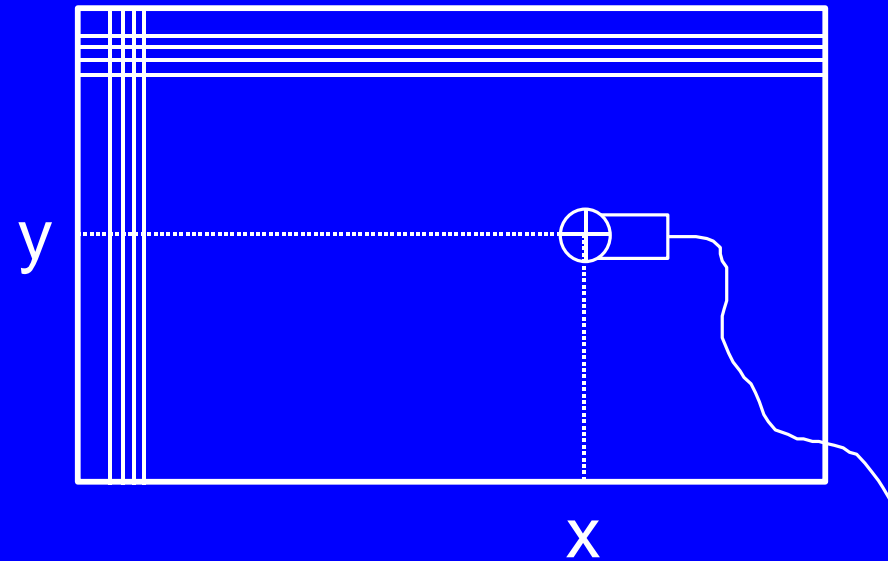
# Digitizing steps

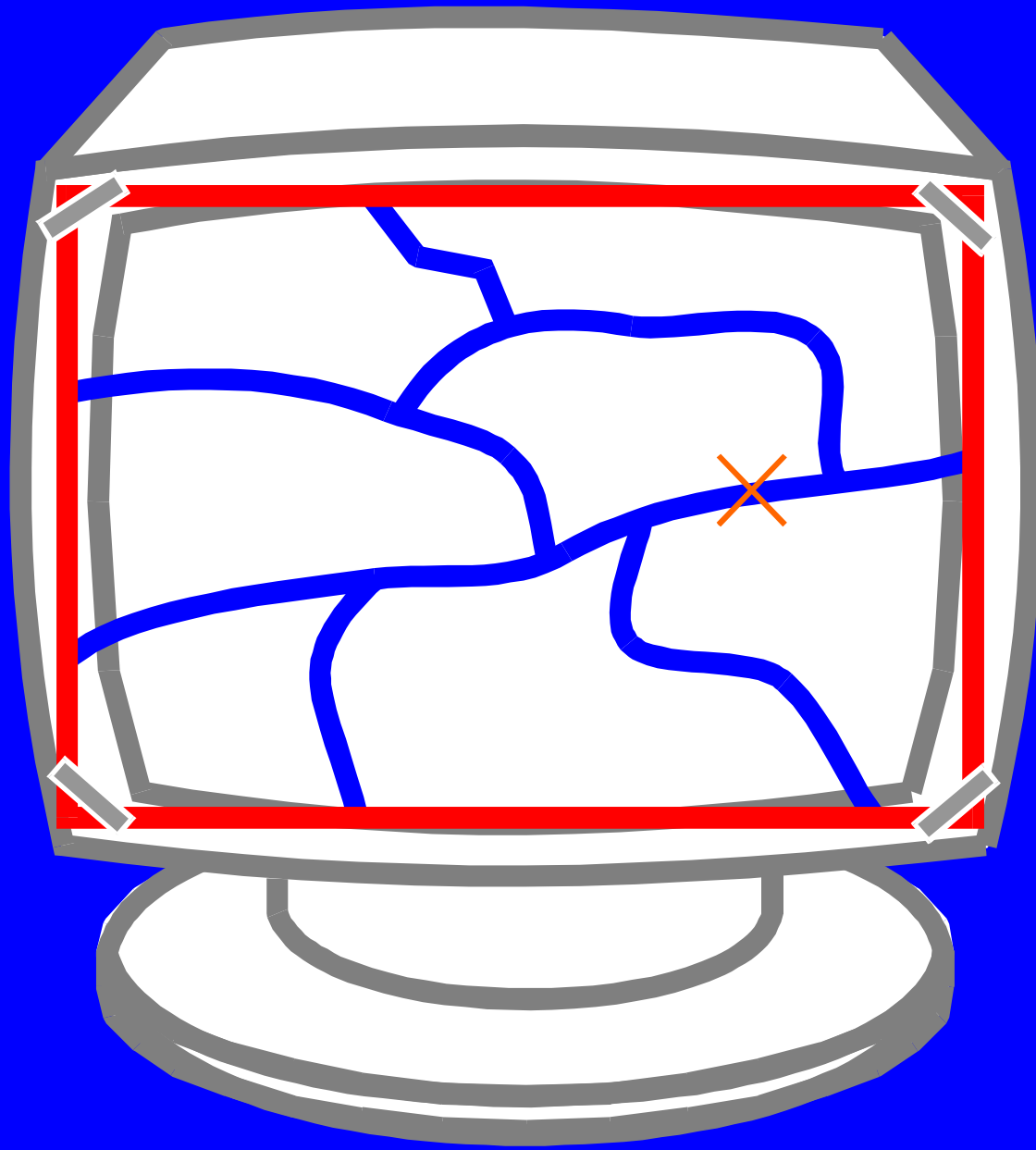
- trace features to be digitized with pointing device (cursor)
- **point mode**: click at positions where direction changes
- **stream mode**: digitizer automatically records position at regular intervals or when cursor moved a fixed distance



# Digitizing table

- grid of wires in the table creates a magnetic field which is detected by the cursor
- x/y coordinates in digitizing units are fed directly into GIS
- high precision in coordinate recording





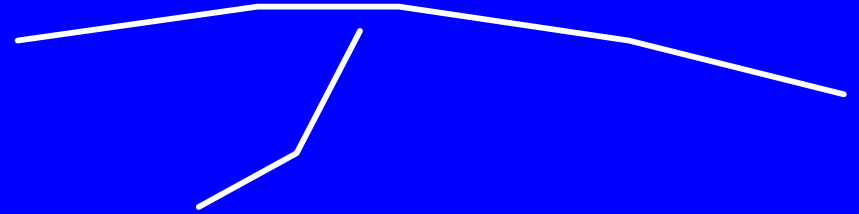
Heads-up  
digitizing I:

features are traced  
from a map drawn  
on a transparent  
sheet attached to the  
screen

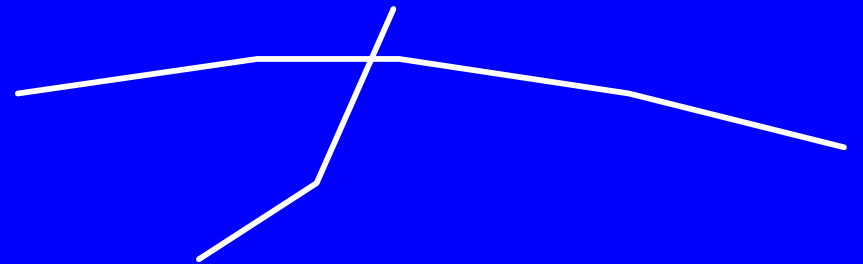
option, if no digitizer  
is available; but:  
accuracy very low

# Digitizing errors

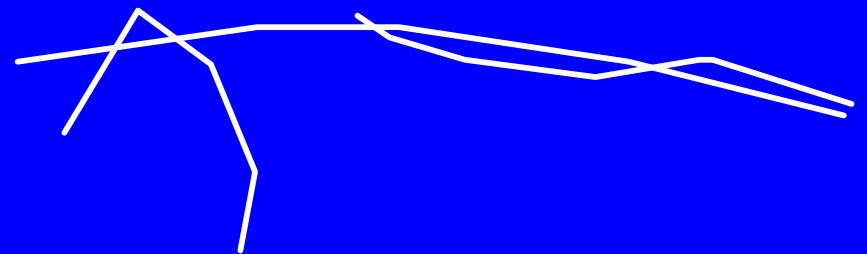
- undershoots



- dangles



- spurious polygons



# Digitizing errors

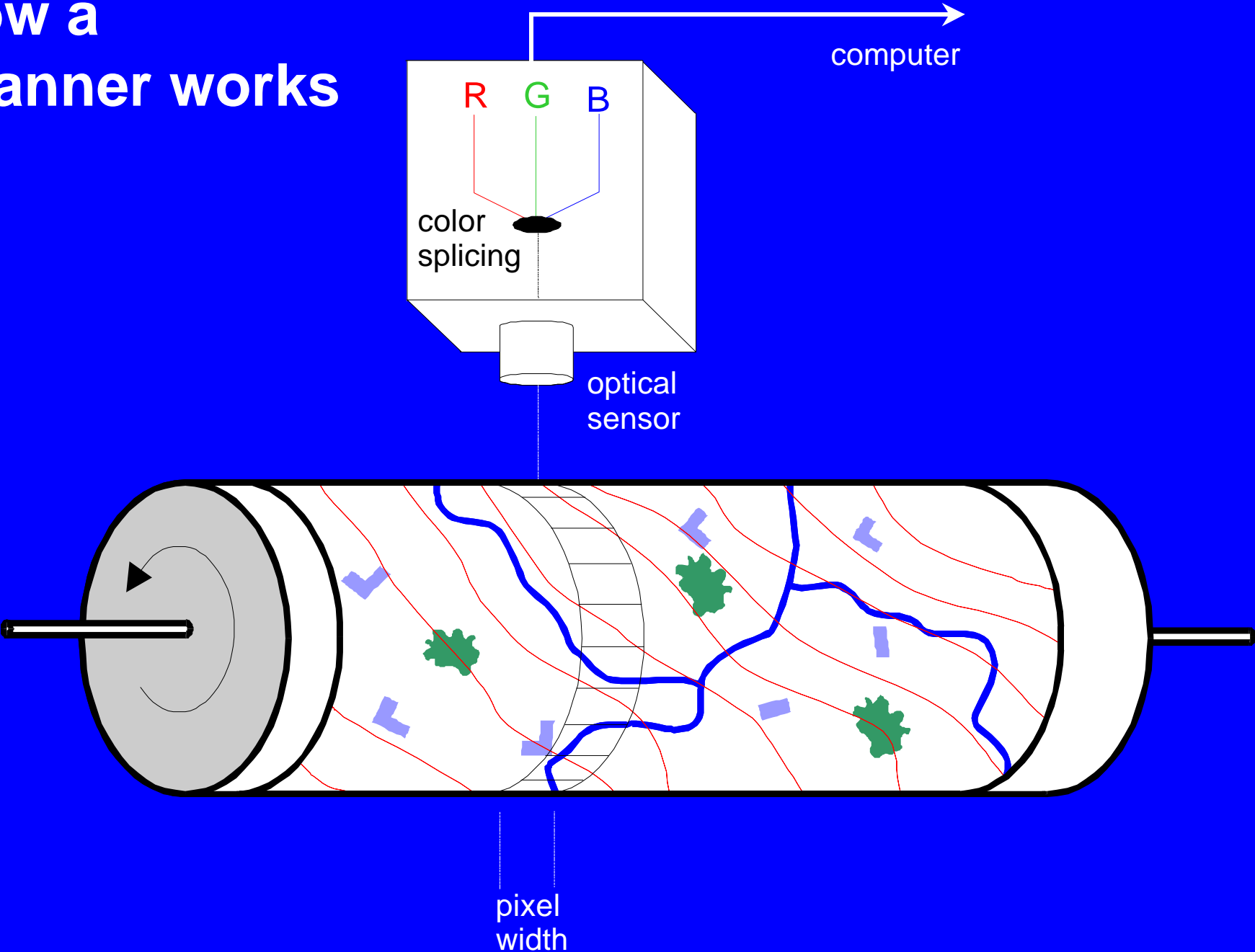
- **any digitized map requires considerable post-processing**
- **check for missing features**
- **connect lines**
- **remove spurious polygons**
- **some of these steps can be automated**

# Scanning

- **electronic detector moves across map and records light intensity for regularly shaped pixels**
- **flat-bed scanner**
- **drum-scanner (pic.)**



# How a scanner works

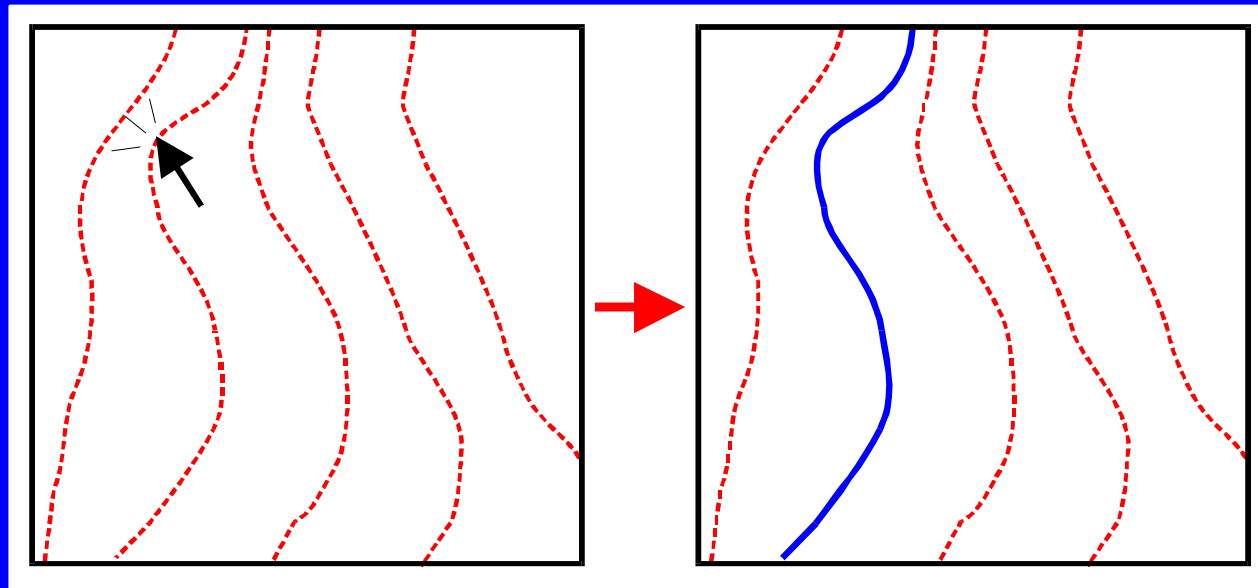


# Scanning

- **scanner output is a raster data set**
- **usually needs to be converted into a vector representation**
  - **manually (on-screen digitizing)**
  - **automated (raster-vector conversion)**
    - line-tracing - e.g., MapScan**
- **often requires considerable editing**

# Raster to vector conversion

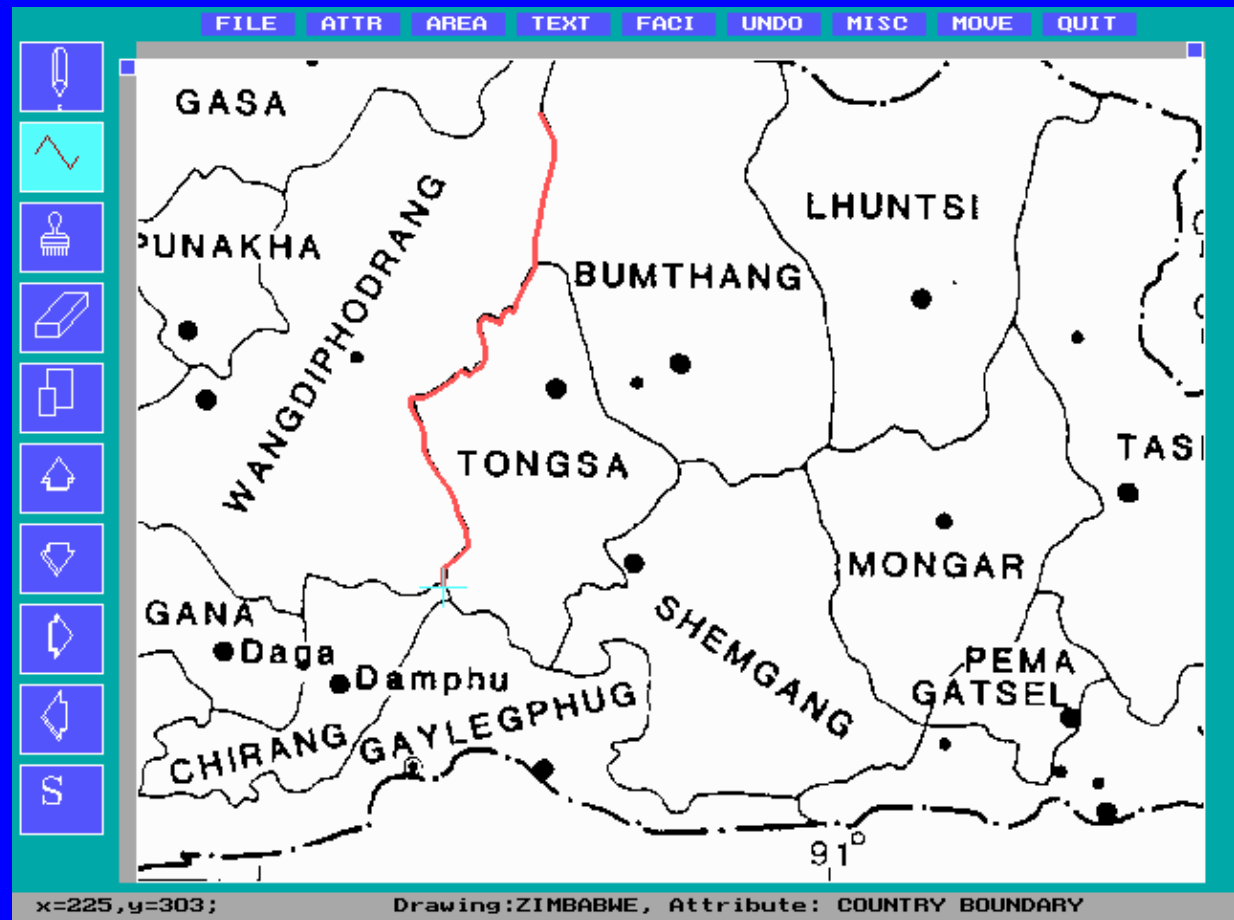
- **automated vectorization:**  
operator sets “global parameters” and system converts entire map
- **interactive line following:**  
operator points at specific line and system follows and converts the line





# Heads-Up Digitizing II:

- Raster-scanned image on computer screen
- Operator follows lines on-screen in vector mode



# Scanning

- **pre-processing can reduce editing required**
- **e.g., trace important features manually first (re-drafting)**
- **scan clearer, simpler map**

# Scanning

- **direct use of scanned images**
- **e.g., scanned air-photos**
- **digital topographic maps in raster format**

# Data input

- **for attribute data:**
  - **spreadsheets**
  - **nlinks to external database management systems (DBMS)**
  - tabulation programs (IMPS, Redatam)**

# **Field data collection: Global Positioning Systems**

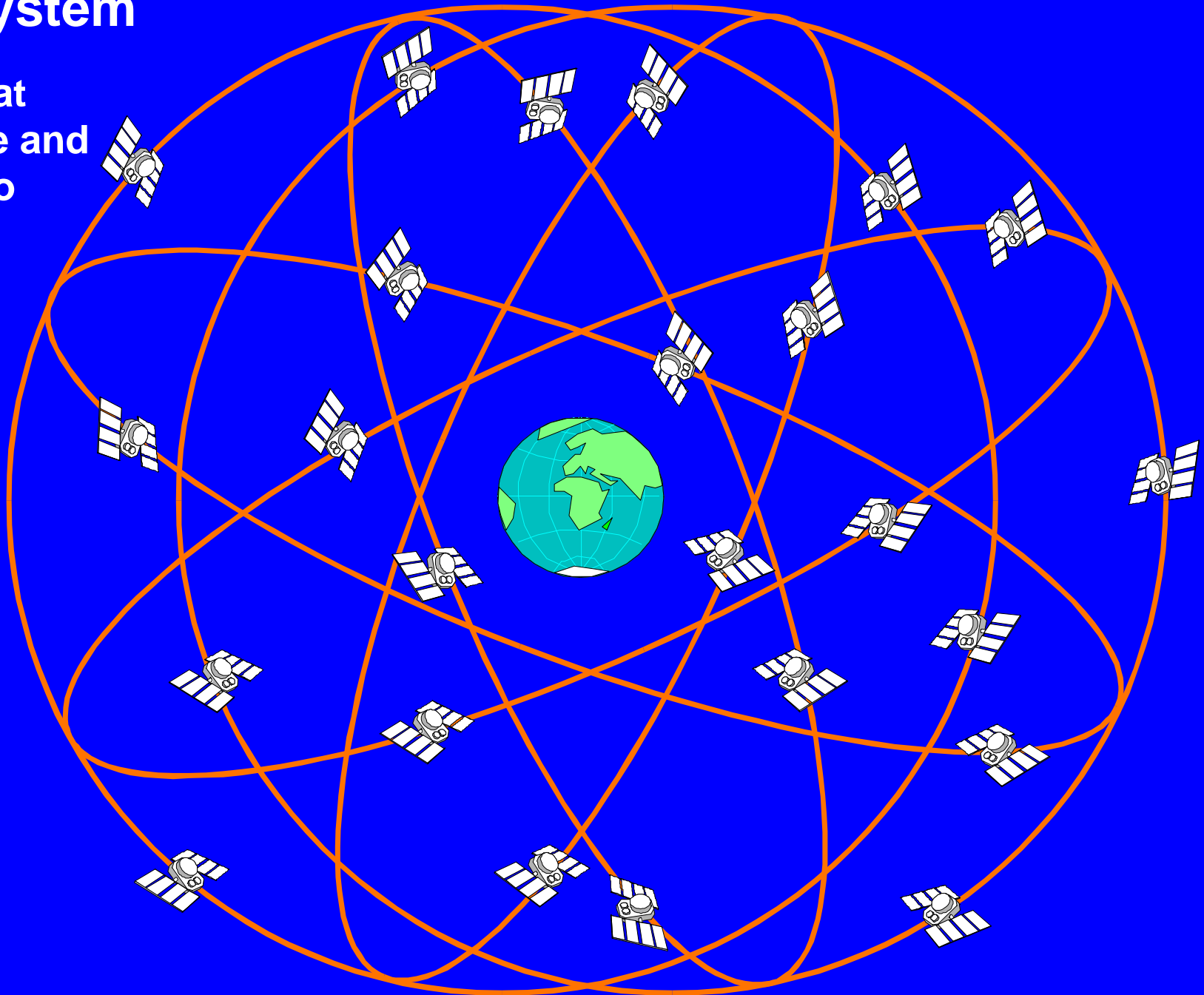
- **determine current position based on signals sent by a number of satellites**
- **accuracy of position can be increased by using a system of control stations (Differential GPS - DGPS)**
- ***GPS* readings are in digital form - can be read directly into the GIS**

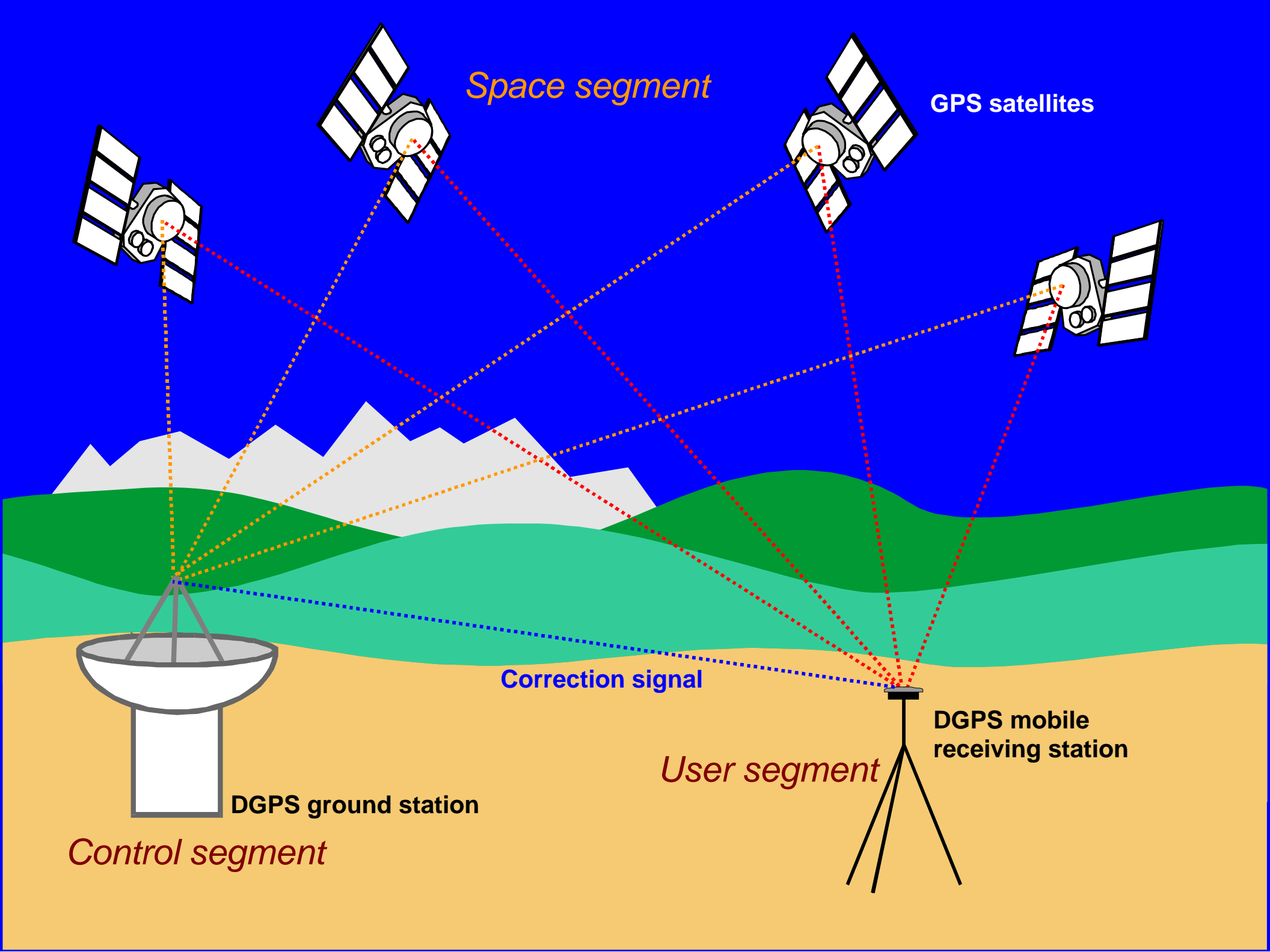
# **Field data collection: Global Positioning Systems**

- **Applications:**
  - **create a village data base**
  - **produce GIS data sets of public facilities**
  - **map census enumeration areas**
  - **locate incidence of disease**
  - **numerous commercial applications**

# The GPS system

24 satellites that  
circle the globe and  
broadcast radio  
signals





*Space segment*

GPS satellites

Correction signal

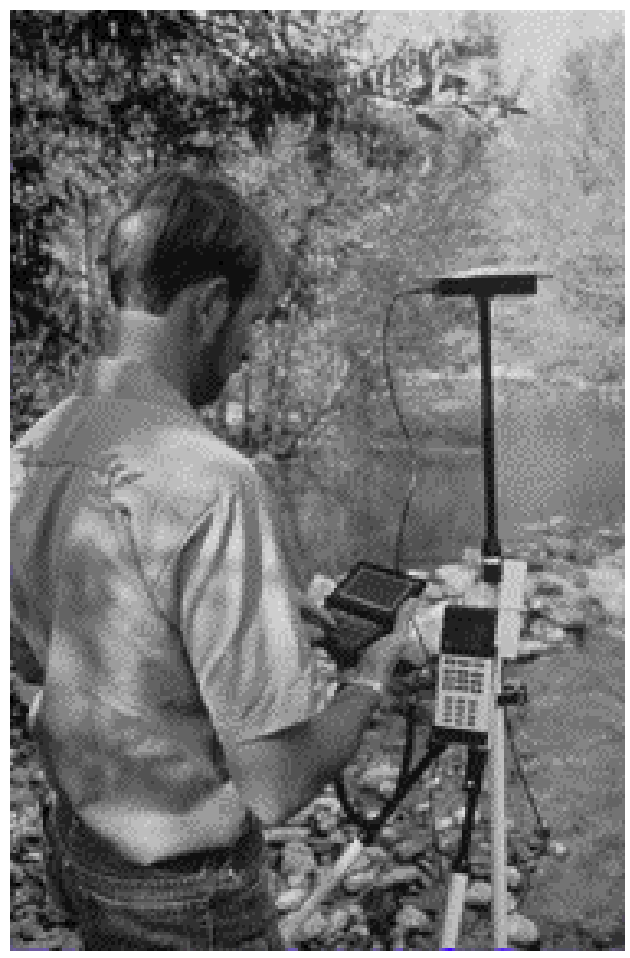
*User segment*

DGPS ground station

DGPS mobile receiving station

*Control segment*





Handheld GPS are now available for about US \$150.

# GPS - Benefits

- **higher accuracy than most traditional field techniques**
- **automatic georeferencing**
- **digital data can be brought directly into computer mapping systems**

# **GPS - limitations**

- **high building densities may cause receiving problems**
- **15-100 m accuracy may be insufficient in urban areas**
- **infrastructure to support Differential GPS is often unavailable and DGPS is expensive**
- **GPS has highest benefits in rural areas**

# Remote Sensing

- includes aircraft, spacecraft and satellite based systems
- products can be analog (e.g., photos) or digital images
- remotely sensed images need to be interpreted to yield thematic information (roads, crop lands, etc.)
- increasingly important source of **statistical information**

# Aerial photography

- traditional end product: printed photos
- today: digital image (scanned from photo)  
in standard graphics format (TIFF, JPEG)  
that can be integrated in a GIS or desktop  
mapping package
- future: fully digital process

# Aerial photography

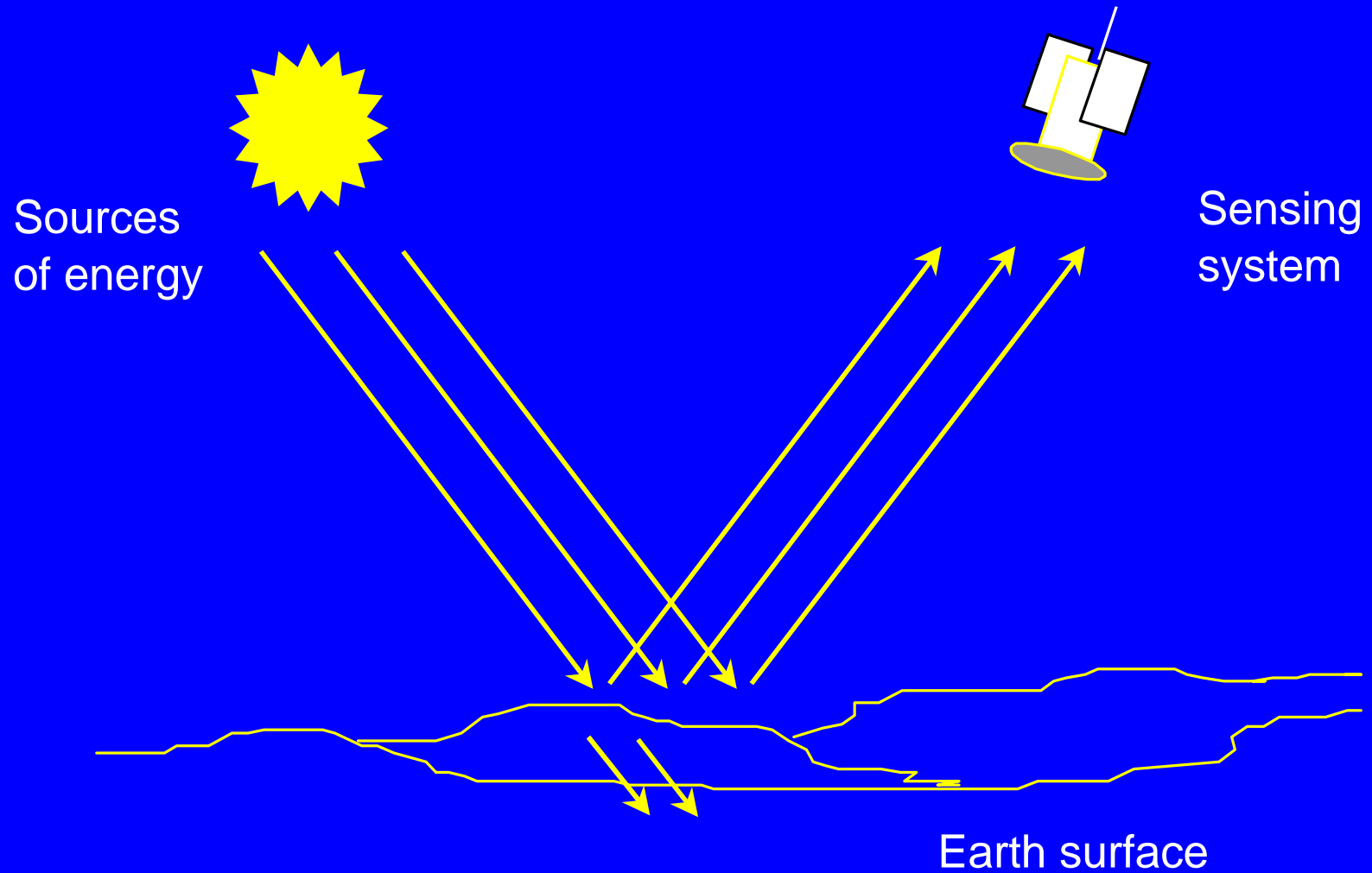
- digital orthophotos
  - corrected for camera angle, atmospheric distortions and terrain elevation
  - georeferenced in a standard projection (e.g. UTM)
  - geometric accuracy of a map
  - large detail of a photograph



- CB map
- 
- 233d.tif
- 233c.tif
- 233b.tif
- 233a.tif



# Remote sensing principle





# Satellite based systems

- Landsat , SPOT, etc.
- also: Russian, Indian, Japanese, European, and Canadian
- panchromatic versus multispectral
- Landsat: 7-8 **spectral bands**  
some in visible spectrum
- new and planned systems have many more (hyper-spectral images)

# Satellite remote sensing

- current systems: resolution of 10-60 meters (Spot, Landsat)
- new systems (1998/99): 0.82 m, 1 m
- allow production of orthomaps comparable to those from aerial photography

Satellite	Resolution (meters) panchromatic/ multispectral	Channels p / m
EarlyBird	3 / 15	1 / 4
QuickBird	0.82 / 3.28	1 / 4
Ikonos (Carterra 1)	1 / 4	1 / 4
Lewis	5 / 30	1 / 3
Clark	3 / 15	1 / 3
Core Software	1.5 / -	1
OrbView-3	1 / 4	1 / 4
IRS-1C	5.8 / -	1 / 4
IRS-1D	5 / 23	1 / 4
KVR 1000	2 / -	1

**Landsat TM image of  
Hongkong  
(bands 7,4,3 - 60m  
resolution) shows  
vegetation in green,  
urban areas in purple/  
white, water in  
blue/black**



**Source: Eosat**



Cairo

Russian KVR 1000 camera system. SPIN-2 - Aerial Images Inc.



**Merged Image of  
Washington D.C.  
combining Landsat TM  
and KVR 1000 data  
(resampled to 5m  
resolution)**

# 1 m resolution Carterra imagery



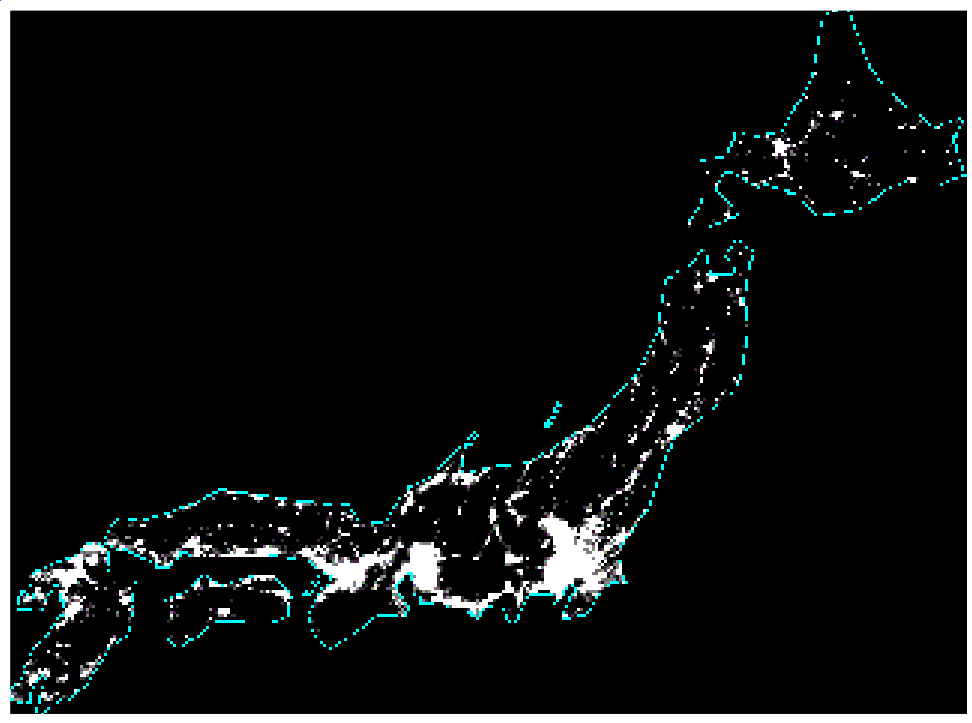
Source: Space Imaging/

# Socioeconomic applications

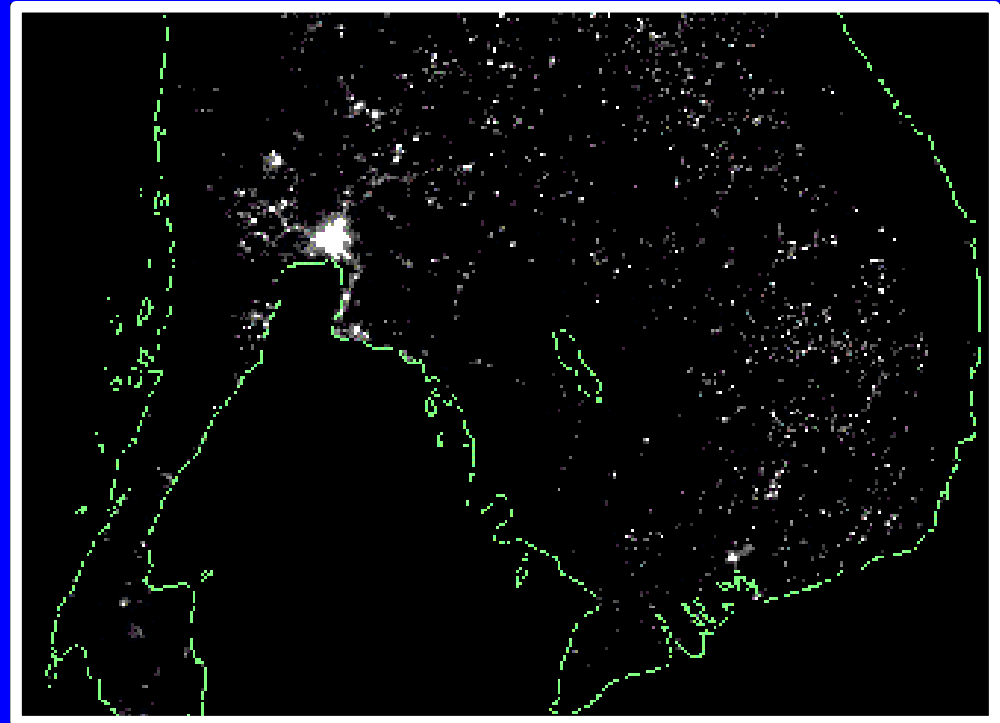
- delineation of newly urbanized areas (e.g., Quito, Manila)
- mapping of villages for population estimation (e.g., Sudan, W-Africa) with Landsat (**rooftop surveys**)
- Defense Meteorological Satellite Program's (DMSP) measures nighttime visible light emissions



# DMSP data

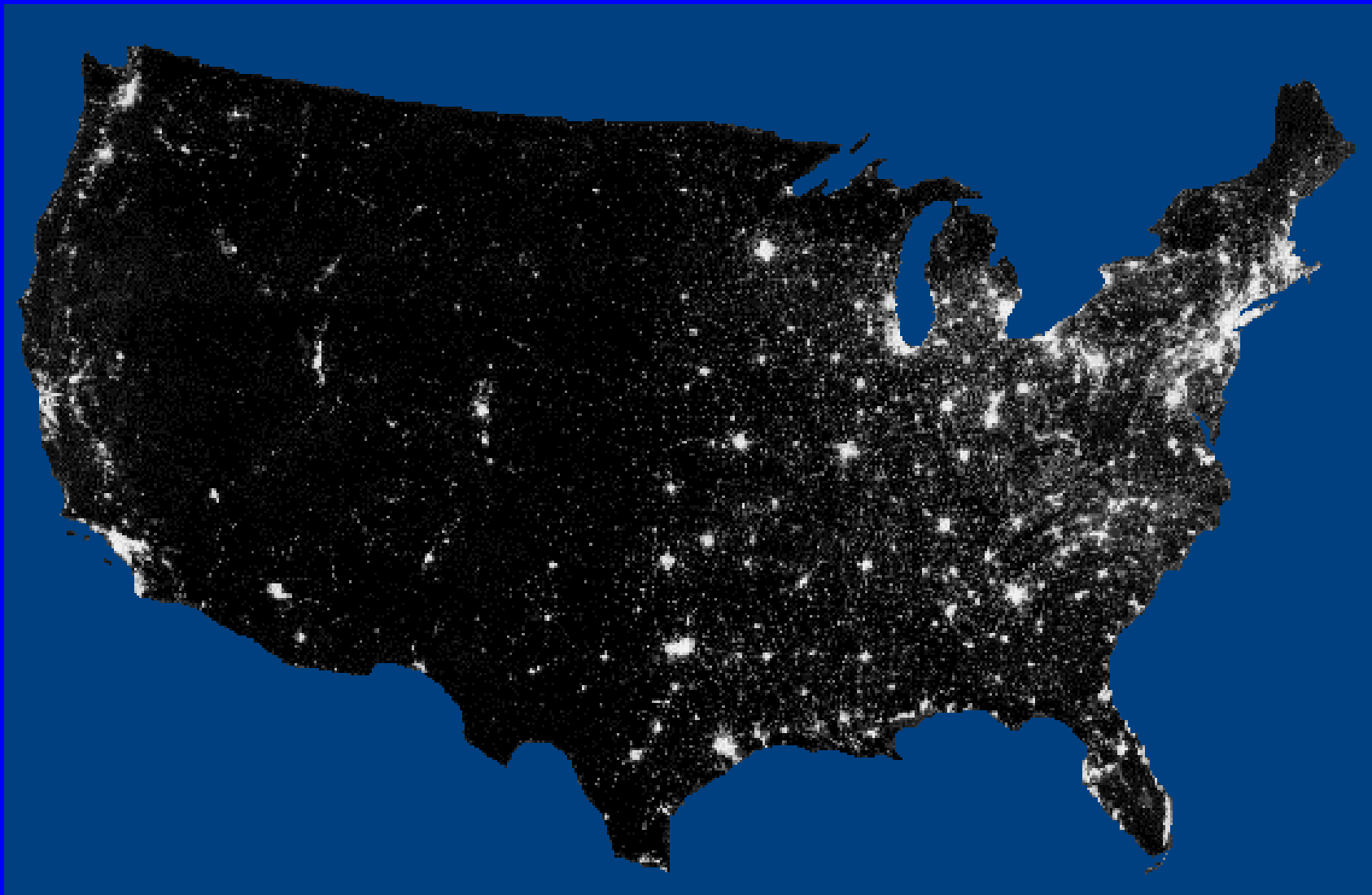


Japan



South-East Asia

# Population Distribution 1980 (mapped census data at the block level)



Source: U.S. Bureau of the Census

# Census from heaven?

- **DMSP data: good for delineating urban/non-urban**
- **too little variation to link to population densities**
- **higher resolution data: usually too expensive and not accurate enough for census-type activities**
- **but: useful source of base maps for EA delineation**